The HCI Benchmark Suite: Stereo And Flow Ground Truth With Uncertainties for Urban Autonomous Driving D. Kondermann, R. Nair, K. Honauer, K. Krispin, J. Andrulis, A. Brock, B. Gussefeld, M. Rahimimoghaddam, S. Hofmann, C. Brenner and B. Jahne (CVPRWORK 2016)



- Stereo and optical flow dataset to complement existing benchmarks
- Representative for urban autonomous driving, including realistic systematically varied radiometric and geometric challenges
- Evaluation of the ground truth accuracy with Monte Carlo simulations
- Interquartile ranges are used as uncertainty measure
- Binary masks for dynamically moving regions are supplied with estimated stereo and flow
- Initial benchmark consists of 55 manually selected sequences between 19 and 100 frames
- Interactive tools for database search, visualization, comparison and benchmarking