Class Specific 3D Object Shape Priors Using Surface Normals C. Häne, N. Savinov and M. Pollefeys (CVPR 2014)



- Dense 3D reconstruction of real world objects
- General smoothness priors such as surface area regularization can lead to defects
- Exploit the object class specific local surface orientation to solve this problem
- Object class specific shape prior in form of spatially varying anisotropic smoothness term
- Discrete Wulff shapes allow general enough parametrization for anisotropic smoothness
- Parameters are extracted from training data
- Directly fits into volumetric multi-label reconstruction approaches
- Allows a segmentation between the object and its supporting grounds
- Evaluated on synthetic data and real world sequences