Segmentation-Based Urban Traffic Scene Understanding

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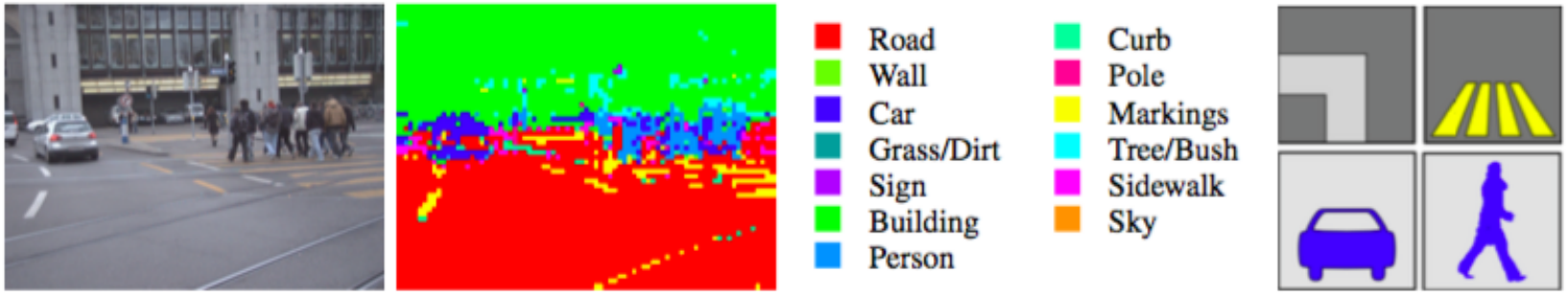

- Proposes a method to recognise the traffic scene in front of a moving vehicle with respect to the road topology and the existence of objects

- Contributions:
  - Uses a two-stage system, where the first stage abstracts the image by a rough super-pixel segmentation of the scene
  - Uses this meta representation in a second stage to construct features set for classifier that is able to distinguish between different road types as well as detect the existence of commonly encountered objects
  - Shows that by relying on an intermediate stage, can effectively abstract from peculiarities of the underlying image data

- Evaluates on two urban data sets, covering day light and dusk conditions