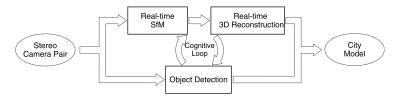
3D Urban Scene Modeling Integrating Recognition and Reconstruction N. Cornelis, B. Leibe, K. Cornelis, and L. V. Gool (IJCV 2008)



Fast and memory efficient 3D city modelling

- Application: a pre-visualization of a required traffic manoeuvre for navigation systems
- Simplified geometry assumptions while still having compact models
 - Adapted dense stereo algorithm with ruled-surface approximation
- Integrating object recognition for detecting cars in video and then localizing them in 3D (not real-time yet)
- 3D reconstruction and localization benefit from each other.
- Tested on three stereo sequences annotated with GPS/INS measurements