The Cityscapes Dataset for Semantic Urban Scene Understanding M. Cordts, M. Omran, S. Ramos, T. Rehfeld, M. Enzweiler, R. Benenson, U. Franke, S. Roth, B. Schiele (CVPR 2016)



- A benchmark suite and large-scale dataset to train and test approaches for pixel-level and instance-level semantic labeling
- Specially tailored for autonomous driving in an urban environment
- Cityscapes is comprised of a large, diverse set of stereo video sequences recorded in streets from 50 different cities
 - 5000 of these images have high quality pixel-level annotations
 - 20000 additional images have coarse annotations to enable methods that leverage large volumes of weakly-labeled data
- Develops a sound evaluation methodology for semantic labeling by introducing a novel evaluation measure
- Evaluates several state-of-the-art approaches on the benchmark