Multi-View 3D Object Detection Network for Autonomous Driving

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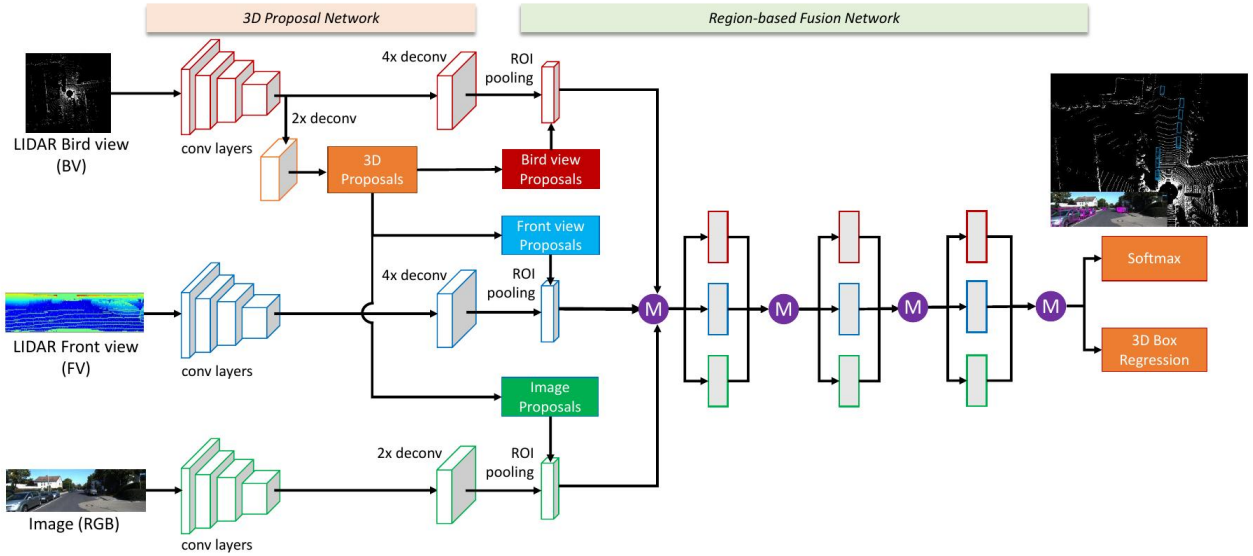

- High-accuracy 3D objection detection in autonomous driving scenario
- Sensory-fusion framework that predicts oriented 3D bboxes using LIDAR point cloud and RGB images
- Encode the sparse 3D point cloud with a compact multi-view representation
- Proposal network generates 3D candidate boxes from bird's eye view representation of the point cloud
- Deep fusion scheme combines region-wise multi-view features and enables interactions between intermediate layers
- Evaluation on the KITTI benchmark outperforming state-of-the-art in 3D localization and 3D detection